

Enabling Component-based Applications in Embedded Systems

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Component-based Development

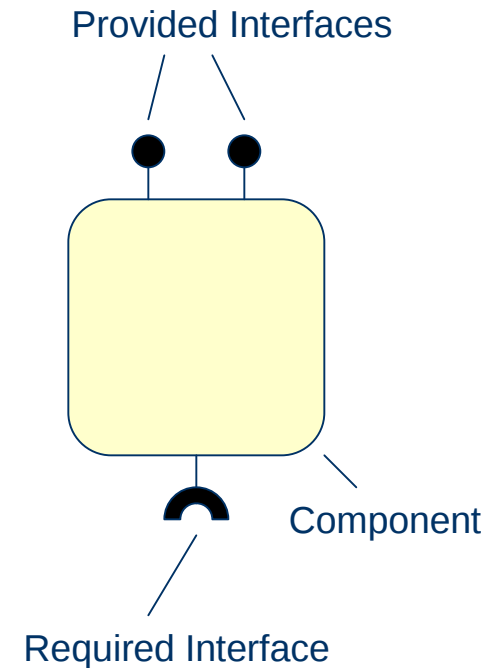
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Components

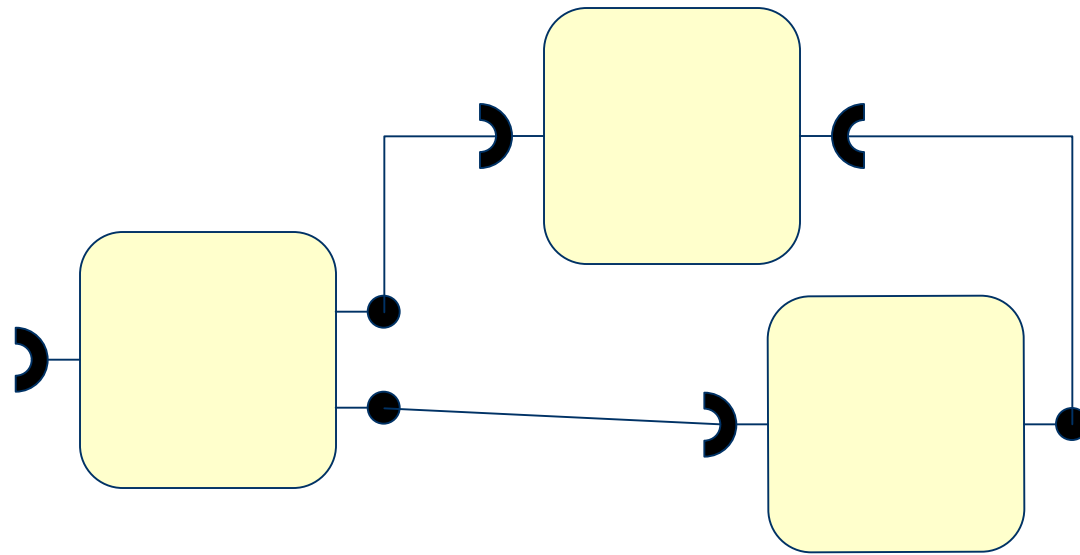
- **“A component represents a modular part of a system that encapsulates its contents and whose manifestation is replaceable within its environment” – [UML]**
 - ▶ **“Modular:” building block**
 - ▶ **“Encapsulates contents:” black box**
 - ▶ **“Replaceable:” implementation vs. interface**

Components (2)

- A component defines its behavior in terms of provided and required interfaces.
- Conformance is defined by these provided and required interfaces.
- Provided and required interfaces: “Ports”

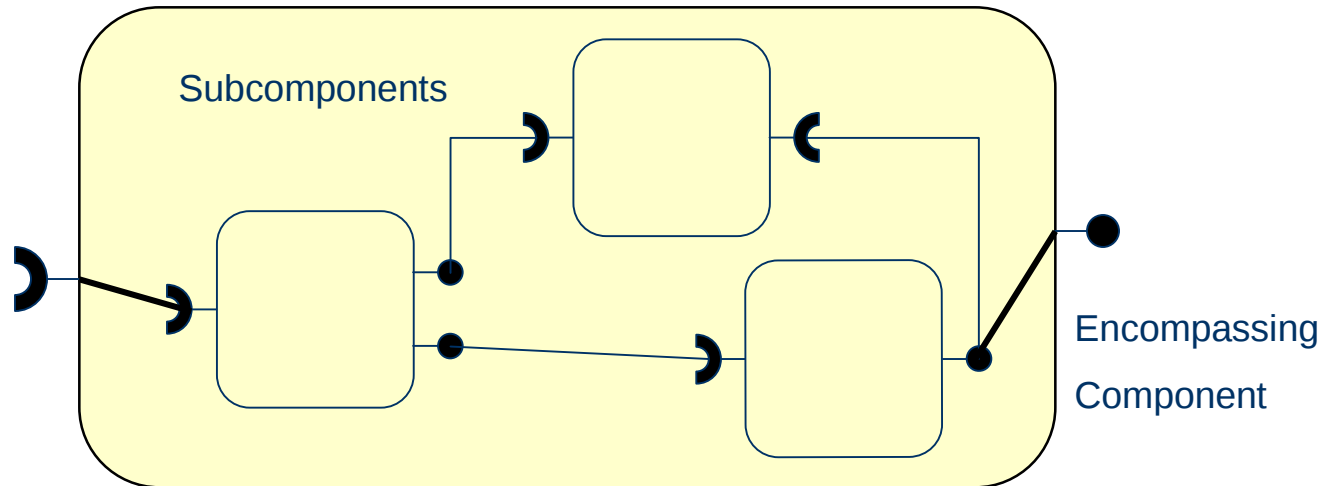


Components (3)



- Larger pieces of a system's functionality may be assembled by reusing components as parts in an assembly, and wiring together their required and provided interfaces.

Hierarchical Assemblies



- **Assemblies are components!**

- ▶ Assemblies “implement” a specific component interface
- ▶ Mapping of component ports and properties to subcomponents
- ▶ Assembly can then be reused as a component

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Lightweight CCM

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Lightweight CCM

- **Original CCM**

- ▶ **Oriented towards multi-tier architectures**
- ▶ **Based on Enterprise Java Beans**
 - **plus ports!**

- **Lightweight CCM**

- ▶ **Upwards compatible subset of CCM**
- ▶ **Retains component model**
 - **Ports, Assemblies**
- ▶ **Removes “business components” features**
 - **Persistence, Transactions, Introspection**
- ▶ **Reduced footprint, more suitable for embedded systems**

Lightweight CCM (2)

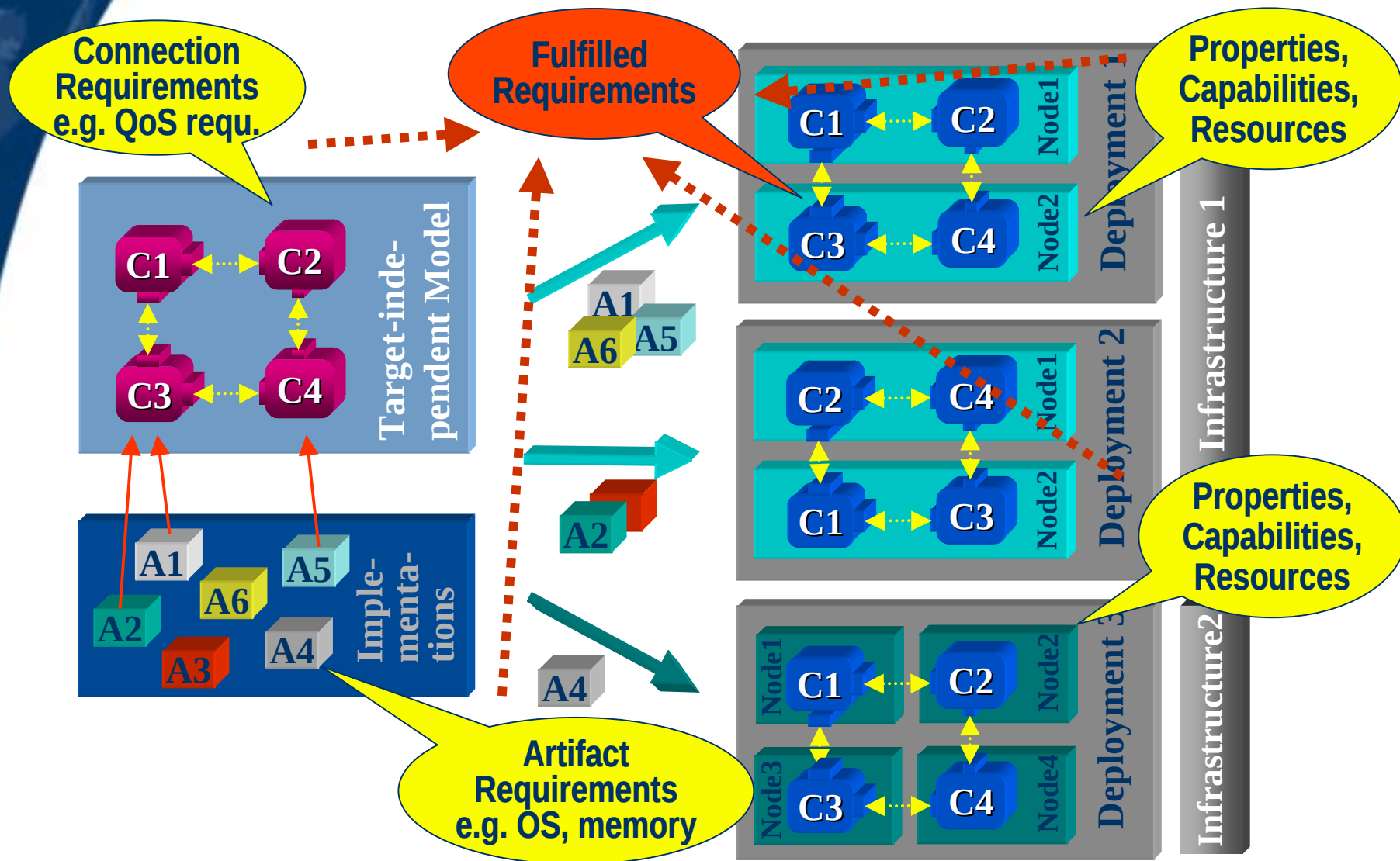
- **Uses “Deployment and Configuration” specification**
 - ▶ Replaces CCM’s “Packaging and Deployment” chapter
- **Supports ...**
 - ▶ Hierarchical assemblies
 - ▶ Resource management
 - ▶ QoS characteristics
 - ▶ Automated deployment
 - ▶ Vendor-independent deployment infrastructure

Deployment and Configuration of Component-based Applications

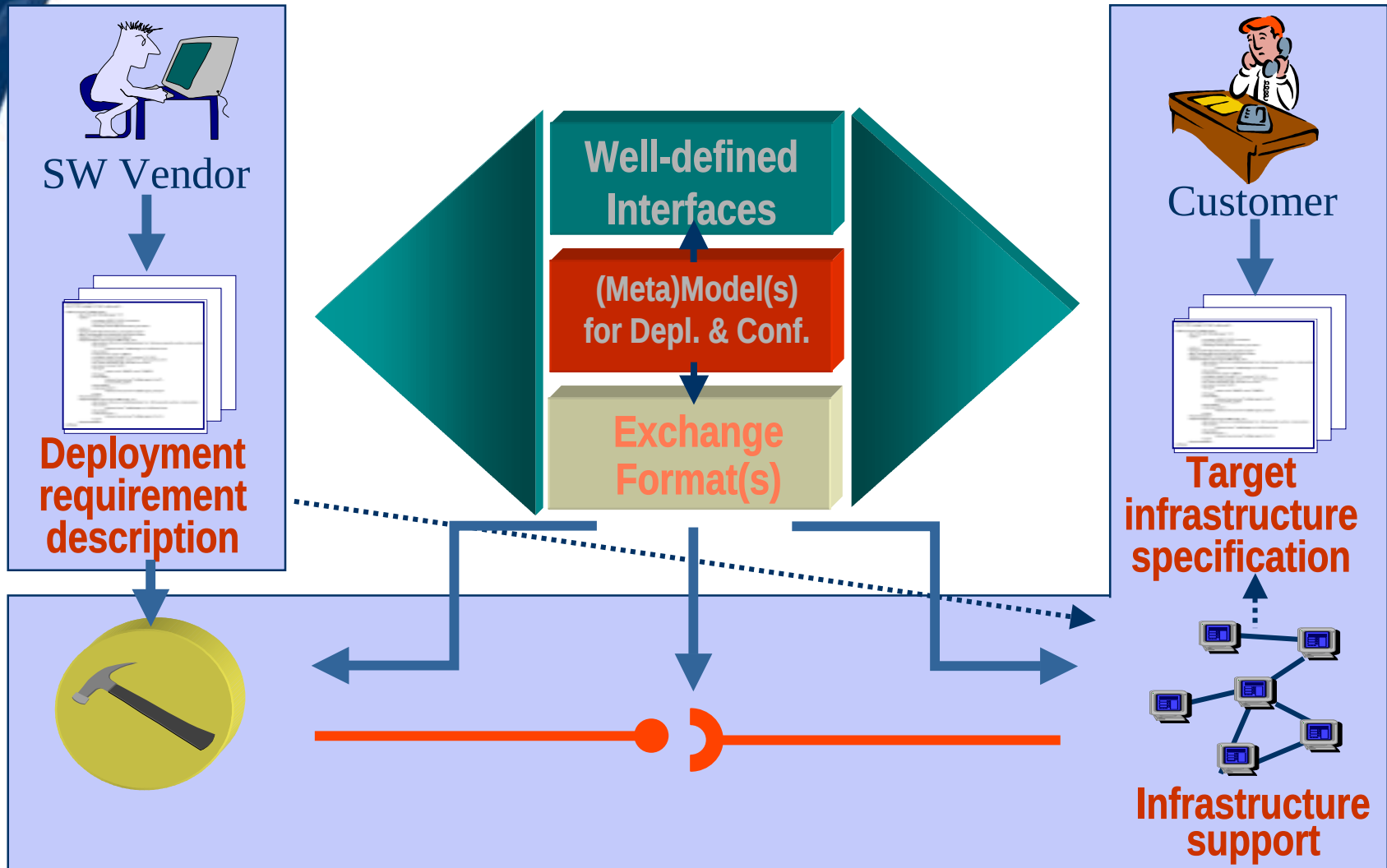
“D+C”

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Deployment Ideas



Deployment Ideas (2)



Deployment Ideas (3)

- **Component Packages**
 - ▶ **ZIP files with artifacts and XML metadata**
 - ▶ **May contain alternative implementations**
 - **For different hardware, and/or**
 - **With different QoS characteristics**
 - ▶ **Reusable by other packages**
- **Hierarchical Assemblies**
- **Resource model**
 - ▶ **Implementations express requirements**
 - **CPU, OS, Devices, communication bandwidth**
 - ▶ **Target Domain expresses resources**
 - ▶ **Well-defined matching process**

D+C Deployment Model

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Separation of Concerns

● Three Model Slices

▶ Component Model

- Metadata to describe component-based applications
- “Repository Manager” interface for installing, maintaining and retrieving Component Packages

▶ Target Model

- Metadata to describe available resources
- “Target Manager” interface for accessing and tracking resources

▶ Execution Model

- Metadata to describe “Deployment Plan”
- “Execution Manager” interface to execute applications according to plan

Compliance Points

- **Four independent compliance points**
 - ▶ **Repository Manager, Target Manager, Execution Manager**
 - Distinct functionality
 - Expected to be part of a COTS deployment suite
 - ▶ **Node Manager**
 - Responsible for intra-node deployment, as directed by the Execution Manager
 - Hardware, OS, ORB specific
 - Implemented by node vendor with little effort
- **Each “Manager” can be replaced separately**

Phases of Deployment

● Four phases of Deployment

▶ Installation

- Package is installed in the Repository

▶ Planning

- Component requirements are matched against available resources, resulting in a Deployment Plan

▶ Preparation, Launch

- Resources are allocated
- Artifacts are loaded onto nodes
- Components are instantiated, interconnected, and started
- Separation between preparation and launch left open, to allow for a wide range of options (preload, early instantiation vs. late loading)

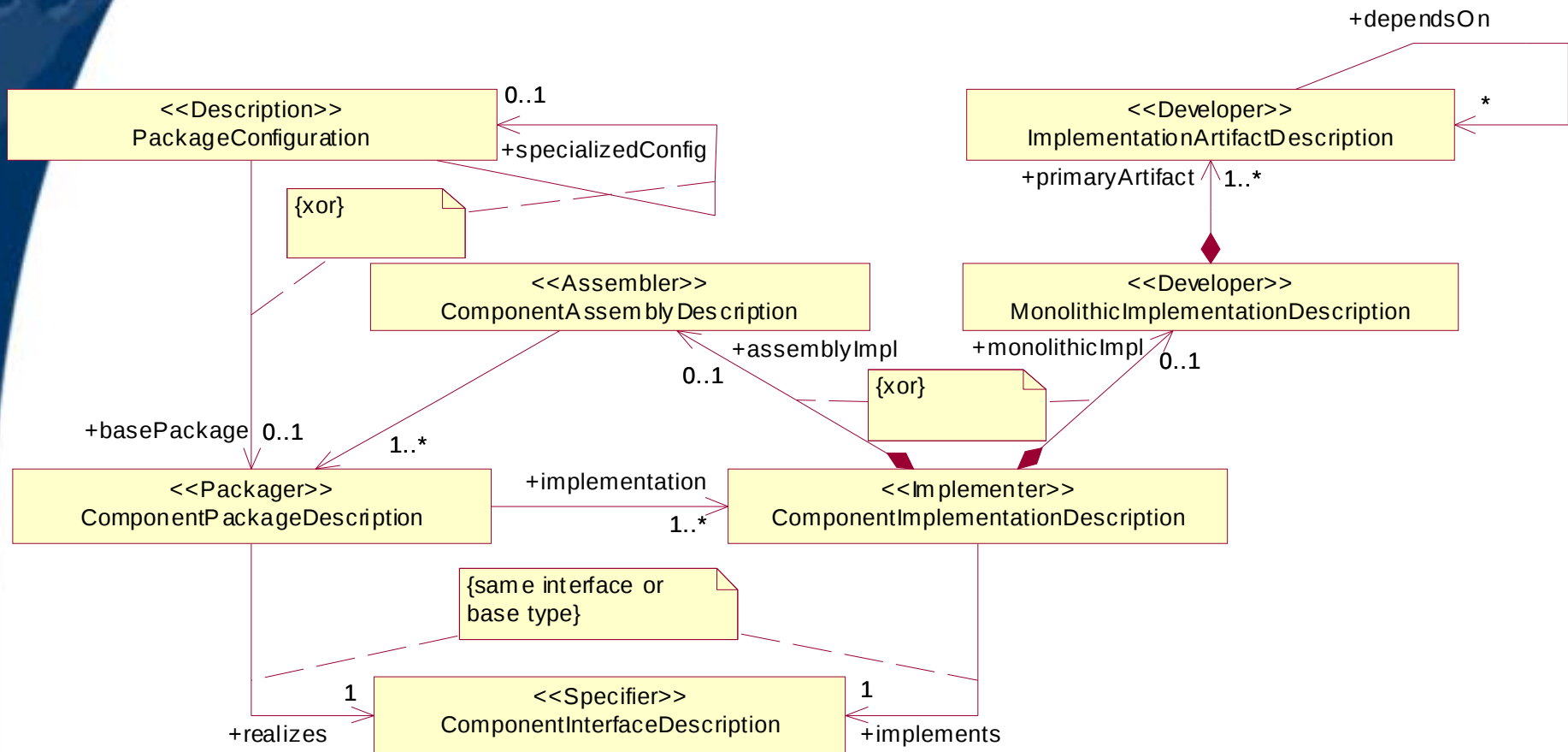
Planning

- **Planning involves ...**
 - ▶ Requirement vs. Resource matching
 - ▶ Selecting acceptable implementations
 - ▶ Mapping implementations to Nodes
 - ▶ Results in Deployment Plan: A “what goes where” script, with configuration
- **Can be done ...**
 - ▶ **Online**
 - Based on “live” resource data
 - For immediate preparation and launch
 - ▶ **Offline**
 - Based on a known set of available resources
 - For storage and later use / reuse

D+C Component Model

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Component Data Model



Component Package

- **Package Configuration**

- ▶ **Configures an application's properties, independent of implementation choice**
- ▶ **Selects among alternative implementations**
 - E.g., "Latency less than 50ms"

- **Component Package Description**

- ▶ **Describes one or more alternative implementations**
 - E.g., for Windows, Linux, Java, FPGA ...

- **Component Implementation**

- ▶ **Assembly-based or Monolithic**
- ▶ **Describes QoS characteristics**

Component Implementation

- **Monolithic implementation**
 - ▶ Usually compiled code
 - ▶ Describes hardware requirements
- **Assembly-based implementation**
 - ▶ Set of interconnected subcomponents
 - Instantiates subcomponents from Packages
 - “Sub-” packages may be included or referenced
 - ▶ Describes interconnection requirements (bandwidth)
 - ▶ Expresses QoS requirements on subcomponents, to satisfy its own
 - ▶ Hardware-independent

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D+C and Embedded Systems

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D+C and Embedded Systems

- **Limited XML Parsing**

- ▶ Only the Repository Manager needs an XML parser, to read “off-line” packages
- ▶ Other information is passed “on-line”, using IDL-defined data structures

- **Central Services**

- ▶ Repository Manager, Target Manager, Execution Manager are singleton services
- ▶ Node Managers can be small, no “intelligence” necessary

- **Planning done locally**

- ▶ No interaction with nodes

Round-trip Minimization

- **Round-trips incur latency**
 - ▶ **Avoid sequential, synchronous invocations**
- **Minimize round-trips**
 - ▶ **Only three round-trips between Execution Manager and Node Managers during application launch:**
 - **First round-trip: node managers return “provided” references for each component**
 - **Second round-trip: execution manager sends references to “uses” ports for each component**
 - **Third round-trip: “start” signal**
 - ▶ **These steps can be parallelized**
 - **EM sends invocations in parallel, then waits for all replies (e.g., using AMI)**

Case Study: SCA Evolution

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SCA Introduction

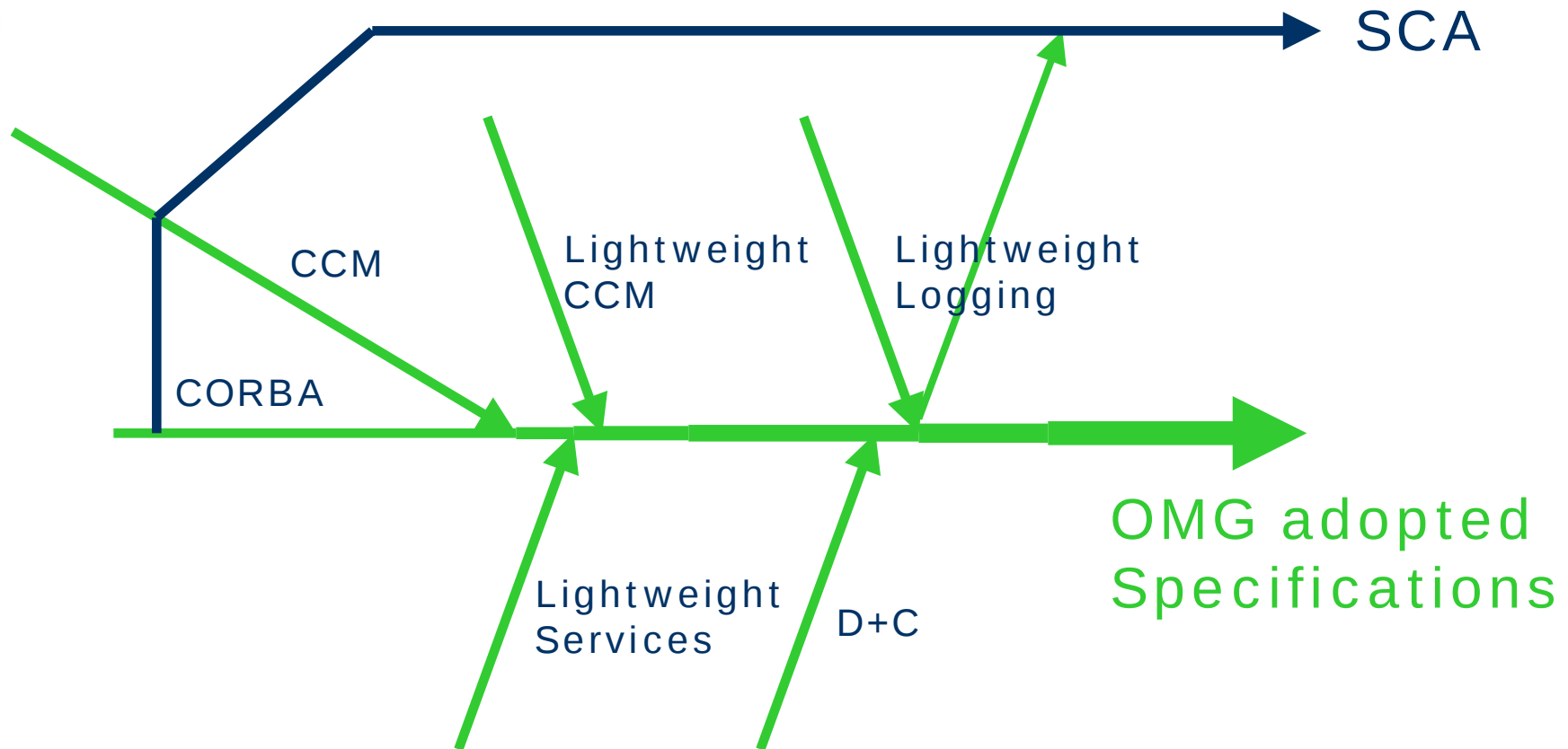
- **Software Communications Architecture (current version 2.2.1)**
 - ▶ **CORBA-based component-oriented middleware**
 - “Resource” components
 - Assemblies of interconnected resources
 - ▶ **XML metadata similar to CCM**
 - ▶ **Basic hardware capacity model**
 - ▶ **Automated deployment**
 - Inspired D+C effort
- **Compliance mandatory for future JTRS Software Radio systems**

SCA History

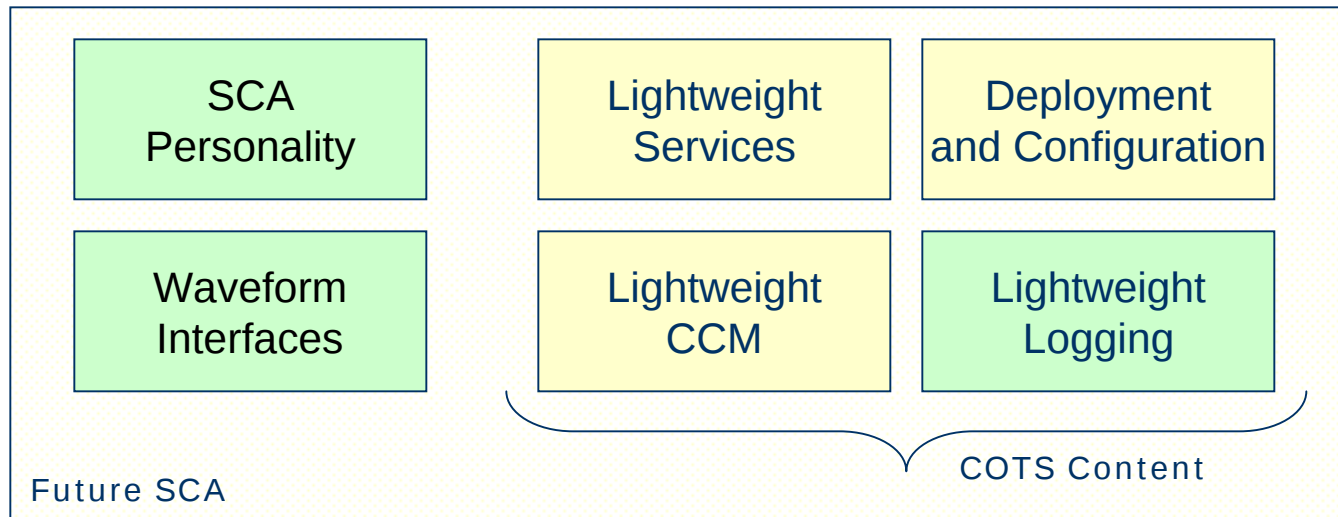
- **SCA pioneered component-based development in embedded systems**
 - ▶ Branched from CCM during finalization
 - ▶ Added important concepts of its own
- **OMG specifications are catching up, exceeding SCA functionality**
 - ▶ Lightweight CCM, Streams for CCM, Lightweight Log, Lightweight Services, D+C
 - ▶ Combine efforts in component-based embedded system development

SCA, OMG Timeline

- Leverage OMG standardization efforts



COTS SCA



- Leverage existing specifications
- Increase COTS Content in SCA
- Focus on Software Radio domain-specific aspects

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Summary

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Summary

- **Lightweight CCM and D+C**
 - ▶ Evolution of original CCM
 - ▶ Enable distributed, component-based Applications — not only in embedded systems
 - ▶ E.g., applicable to Software Radio (SCA)
- **Status**
 - ▶ Adopted OMG specifications
 - ▶ Currently being finalized
 - ▶ Implementations expected later this year